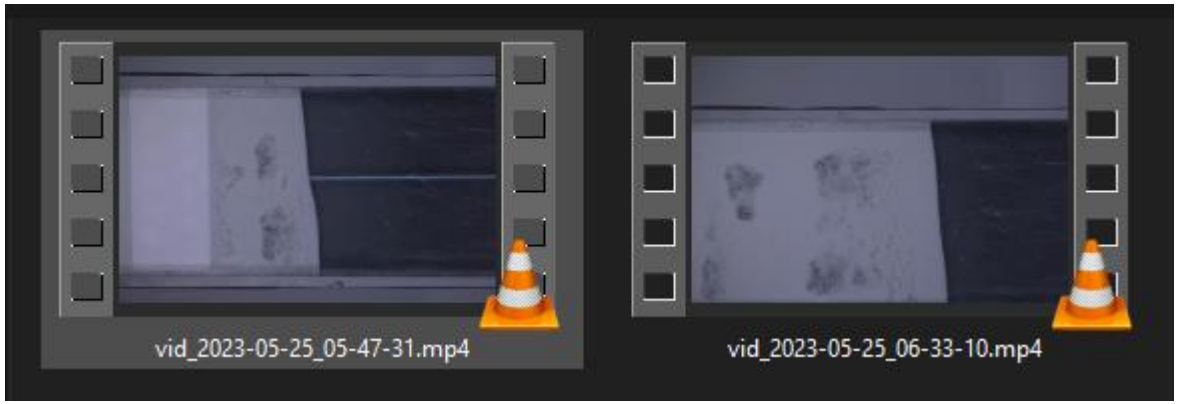
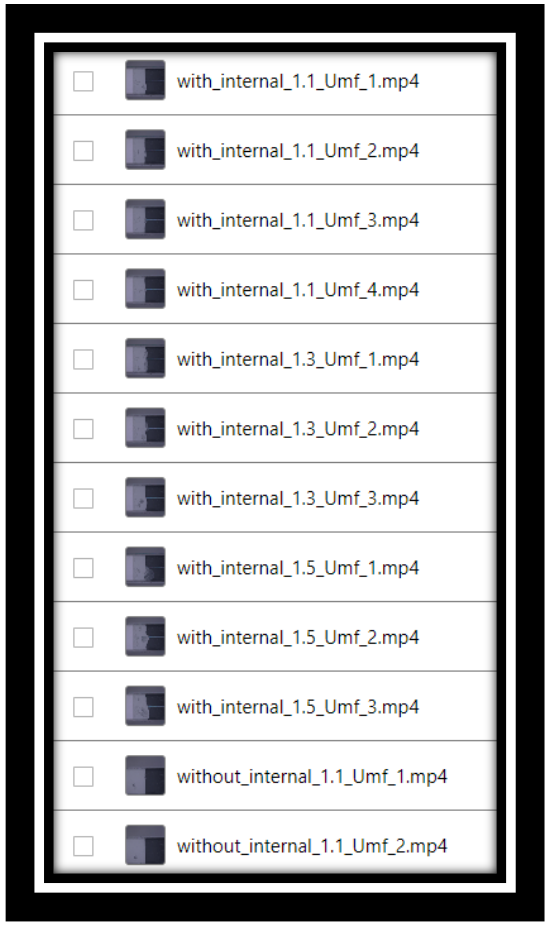
# Data Analysis – Session 1

08.06.2023

# Step 1) File renaming

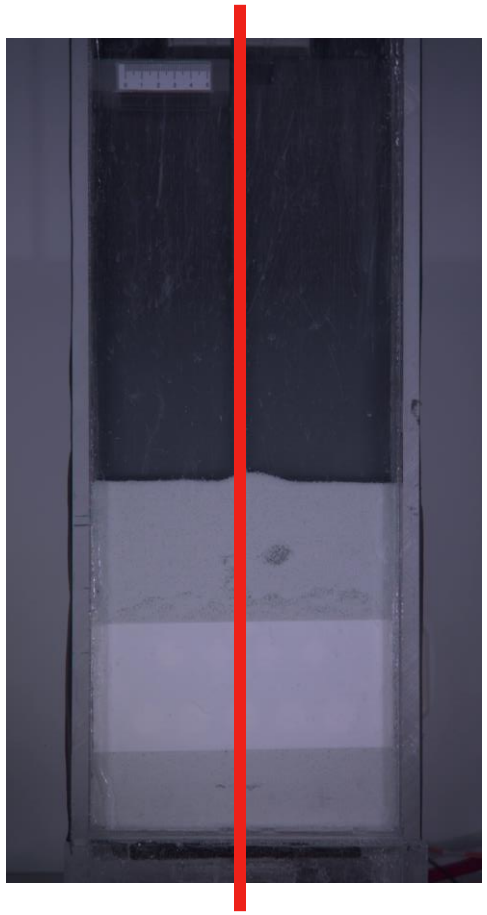
- Give the files meaningful names to simplify evaluation



# Step 2) Crop and align

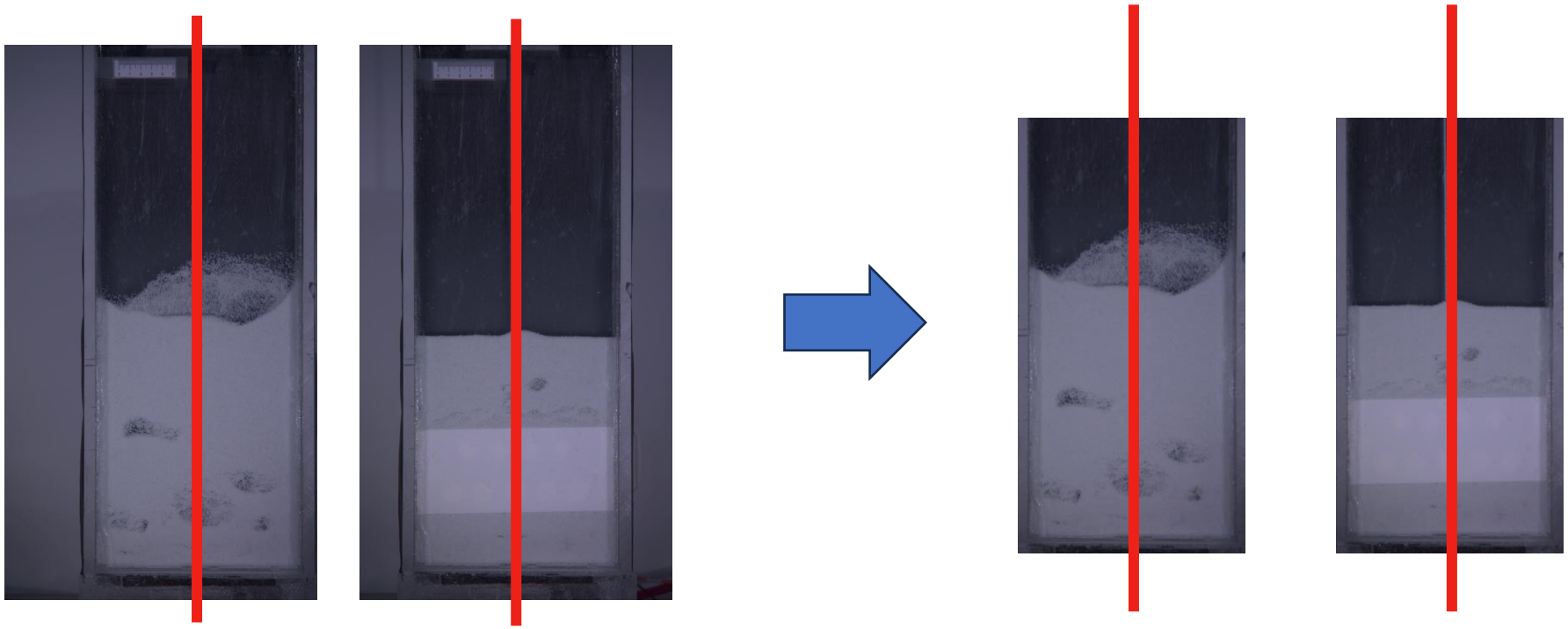
without_internal_1.5_Umf_3.mp4



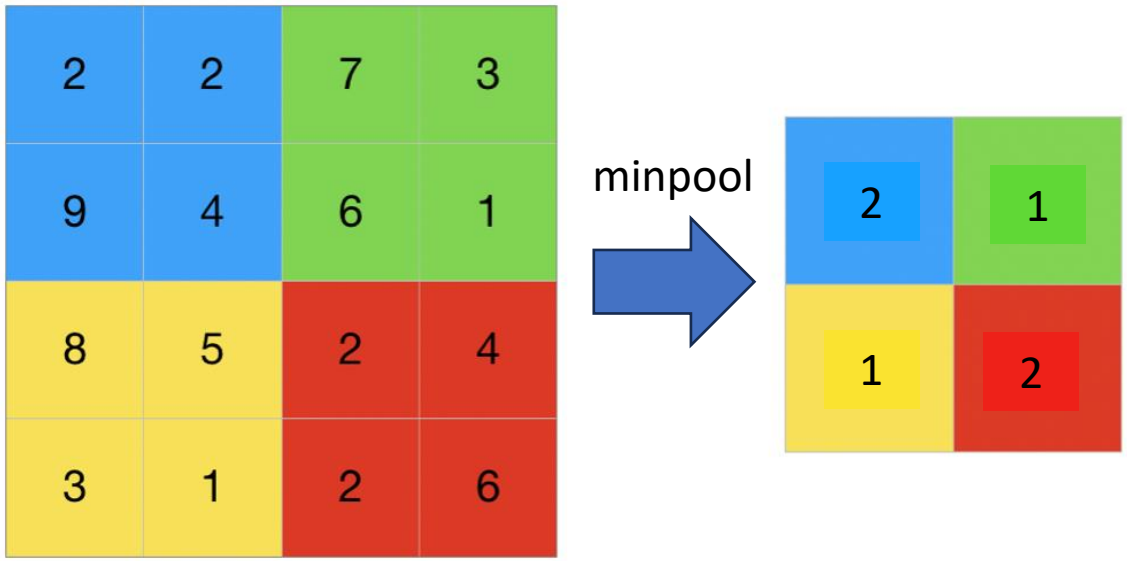
with_internal_1.1_Umf_1.mp4

- Both measurements are from the same group, but their alignment is different
- Use tool / fix point to give every measurement the same alignment

# Step 2) Crop and align



# Reduce resolution with minpool




- Minpool reduces a 2x2 pixel grid to one pixel. The resulting pixel has the minimum value of the previous 4 pixels.
- By performing the operation, the resolution get's halved
  Example: 1000x1000 -> 500x500

# Reduce resolution with minpool

- Reasoning: Some bubbles are hardly visible. Only a few darker pixels indicate their existence.
- Normal down sampling would average pixel values, darker values would vanish.

# Reduce number of frames

- You have recorded 1000 frames for each measurement
- To reduce file size and processing time, 100 frames of each measurement have been chosen for processing

# Save as h5 file


- File format from camera: MP4
  MP4 is a format for compressed video
  - Small filesize
  - Data cannot be accessed directly

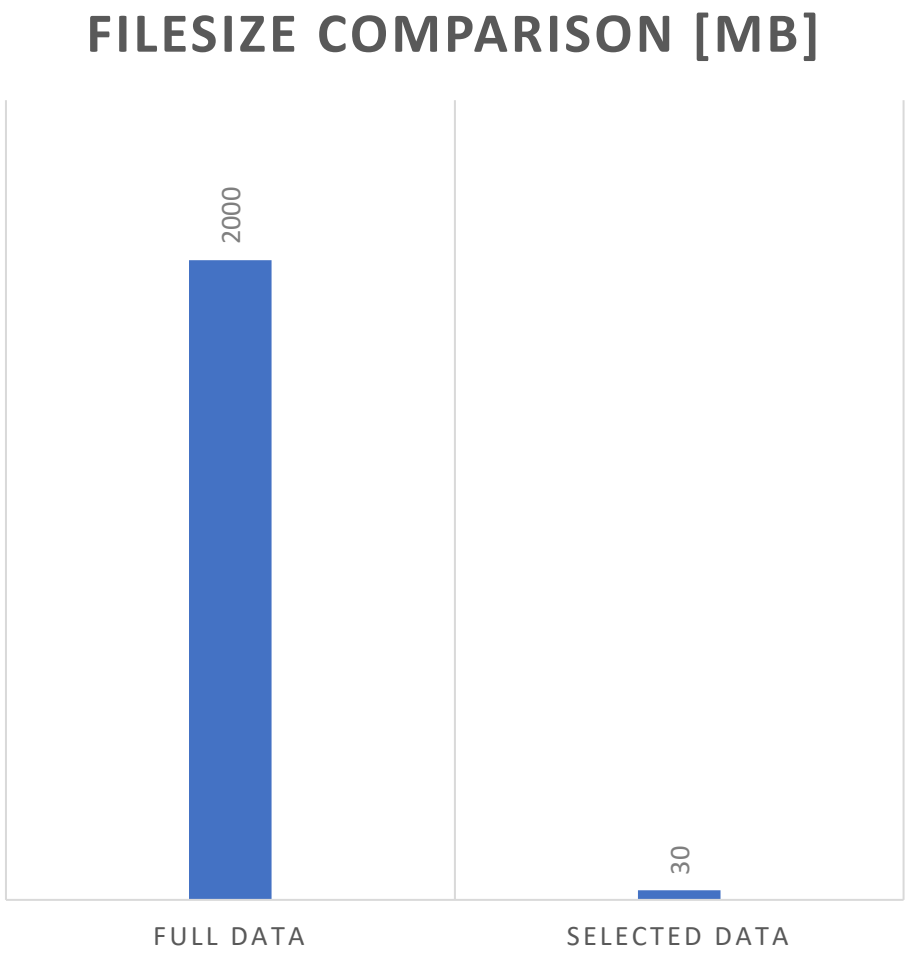
Render mp4 video into a 3D tensor (height * width * frames)
and save into a h5 file

- New file format: H5
  H5 is a container format to store variables
  - Uncompressed
  - Data can be organized by groups and keys

| | | |
|---|---|---|
| /datas | <group> | |
| /datas/data | <group> | |
| /datas/data/vel | <group> | |
| /datas/data/vel/RL | float32 | (112, 112, 500) |
| /datas/data/vel/AP | float32 | (112, 112, 500) |
| /datas/data/sd | float32 | (112, 112, 500) |
| /datas/par | <group> | |
| /datas/par/dyns | float64 | (1, 1) |
| /datas/par/venc | <group> | |
| /datas/par/venc/AP | float64 | (1, 1) |
| /datas/par/venc/RL | float64 | (1, 1) |
| /datas/par/FOV | float64 | (1, 3) |
| /datas/par/TE | float64 | (1, 1) |
| /datas/par/TR | float64 | (1, 1) |
| /datas/exppar | <group> | |
| /datas/exppar/Velocity_U_Umf_ | float64 | (1, 1) |
| /datas/exppar/Flowratepercent | float64 | (1, 1) |
| /datas/exppar/Flowratelpm | float64 | (1, 1) |
| /datas/exppar/PulseSequence | bytes8 | (1, 3) |

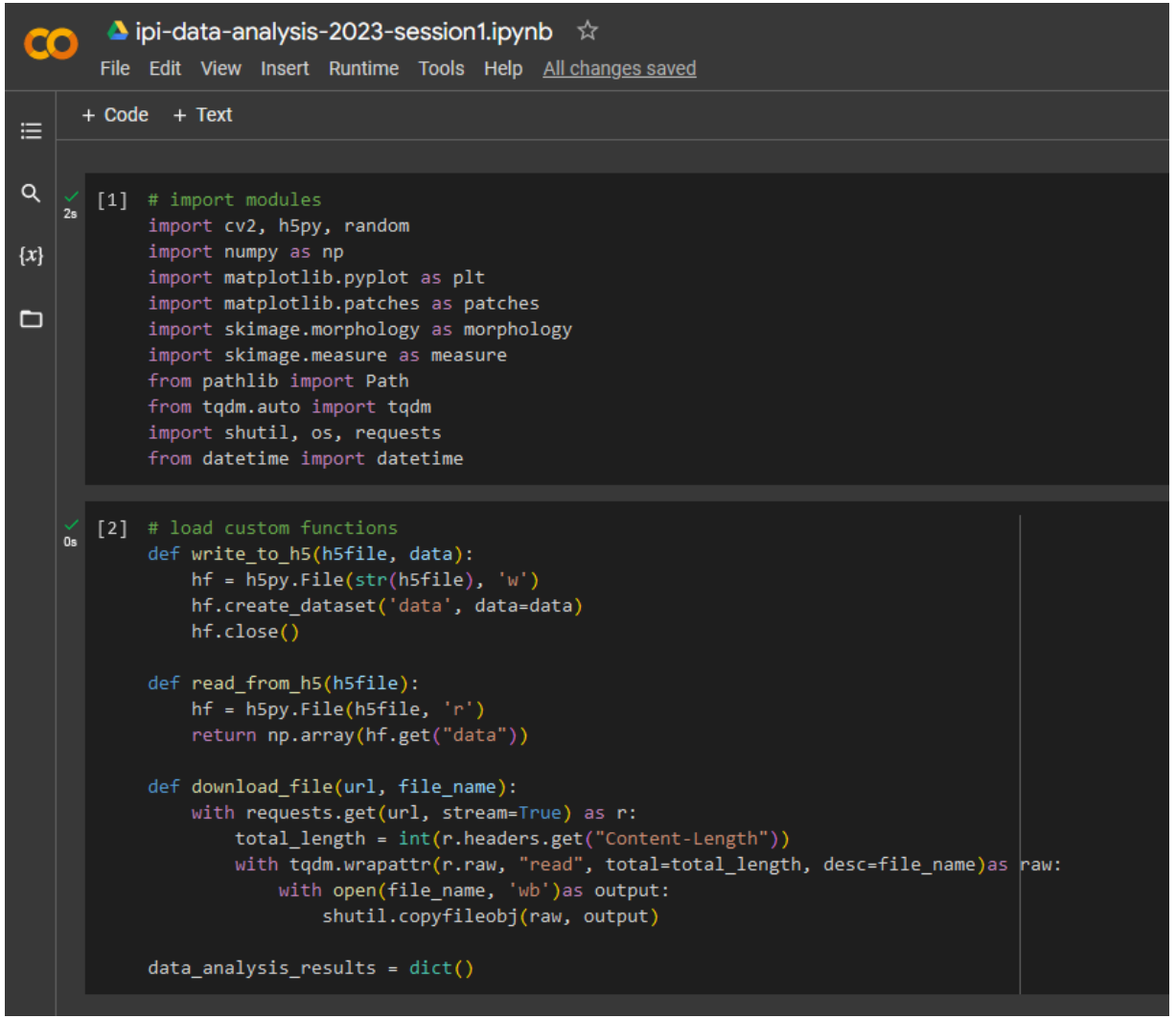
# File size optimization

- With the 1920x1080 resolution and 1000 frames, even with number type uint8 we end up with 2Gb for each recording
- $1920 \times 1080 \times 1000 \times 1\text{byte} = 2.073.600.000\text{bytes}$
- With all the optimizations, we end up with a ~30 Mb file



# Google Colab

- Run Python interactively, step by step
- Run Python on a website without installing it on your computer



# Further resources

- https://www.ipi.tuhh.de/process-imaging/